Zenith Ai

Z to A of intelligence

Robust Deep Learning: Understanding real-world data and data-centric AI.

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2 Robust deep learning by example weighting strategies Definition of example weighting Derivative manipulation (DM) for general example weighting

Robust deep learning by target modification strategies
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 Target definition and target modification approaches
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Why do we need robust deep learning? To learn meaningful patterns under real-world adverse cases.



Horse class: The first three images are deer semantically.



This video is labelled as the person wearing black skirt.



This video is labelled as the person wearing green shirt.

Figure: Display of abnormal training examples highlighted by red boxes.



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Adverse cases in real-world data Out-of-distribution anomalies: Know the unknown

- Some inputs contain only background and no semantic information at all.
- Some may contain a object that does not belong to any class in the training set.



Adverse cases in real-world data In-distribution anomalies: Detect => Ignore or Correct

- Label noise arising from:
 - Noisy annotations: e.g., some images of deer may be wrongly annotated to horse.
 - 2 Missing annotations: we may use some algorithms to predict their labels. If so, the predicted labels are not 100% accurate.
- When an input contains more than one object, it becomes ambiguous without any prior.



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Learning objectives of robust deep learning

What is the meaning of robustness here?

- **To learn meaningful patterns** on semantically clean training data (where noise may exist, however, the semantic matching from observations to annotations is highly correct).
- Without fitting wrong patterns on semantically wrong training data, so that the learning process of a model is not contaminated.
- Generalisation to unseen data.



Robustness against adverse cases What should a learning process ideally look like?



- p_i = p(y_i|x_i) : predicted relevance between an observation x_i and it label y_i.
- We train ResNet-56 on CIFAR-10 with 40% symmetric label noise.

Generalise to unseen data

Build train-validation datasets properly



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Robust learning via example weighting Example weighting is universal in deep learning

We define our interpretation of example weighting [10]:

Definition (Example Weighting). In gradient-based optimisation, the loss's derivative of an example can be interpreted as its effect on the update of a model [3, 1]. Therefore, a derivative's magnitude function can be treated as a weighting scheme from the viewpoint of example weighting.

Accordingly, one technique that leads to a change of the derivative magnitude function, is equivalent to, modifying an example weighting scheme.



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Derivative manipulation (DM) Fundamental research guestions and conclusions

What kind of examples to focus on during training? How to weight them properly?

- 2 A loss function is okay to be non-symmetric, unbounded, or even non-differentiable.
- Is a loss function necessary for deriving the gradient used for back-propagation?
- When a training set contains a higher label noise rate, we should focus on easier training examples for better generalisation!



Standard practice versus DM



Figure: Black and red arrows denote forward process and gradient back-propagation, respectively.



Direction: the same as common losses Analysis of common losses

$$L_{CCE}(x_{i}, y_{i}) = -\log p(y_{i}|x_{i})$$

$$L_{MAE}(x_{i}, y_{i}) = 1 - p(y_{i}|x_{i})$$

$$L_{MSE}(x_{i}, y_{i}) = (1 - p(y_{i}|x_{i}))^{2}, \quad (1)$$

$$L_{GCE}(x_{i}, y_{i}) = \frac{1 - p(y_{i}|x_{i})^{q}}{q},$$

$$\frac{\partial L_{CCE}}{\partial z_{ij}} = \begin{cases} p(y_{i}|x_{i}) - 1, & j = y_{i} \\ p(j|x_{i}), & j \neq y_{i} \end{cases}$$

$$\frac{\partial L_{MAE}}{\partial z_{i}} = p_{i} \times \frac{\partial L_{CCE}}{\partial z_{i}}; \quad (2)$$

$$\frac{\partial L_{MSE}}{\partial z_{i}} = 2p_{i} \times (1 - p_{i}) \times \frac{\partial L_{CCE}}{\partial z_{i}};$$

$$\frac{\partial L_{GCE}}{\partial z_{i}} = p_{i}^{q} \times \frac{\partial L_{CCE}}{\partial z_{i}}.$$

Magnitude: Emphasis Density Function

• Example weighting in common losses

$$w_i^{\text{CCE}} = 2(1 - p_i) \Longrightarrow \psi_{\text{CCE}} = 0;$$

$$w_i^{\text{MAE}} = 2p_i(1 - p_i) \Longrightarrow \psi_{\text{MAE}} = 0.5;$$

$$w_i^{\text{MSE}} = 4p_i(1 - p_i)^2 \Longrightarrow \psi_{\text{MSE}} = \frac{1}{3};$$

$$w_i^{\text{GCE}} = 2p_i^q(1 - p_i) \Longrightarrow \psi_{\text{GCE}} = \frac{q}{q + 1}.$$
(3)

• Our generalised formulation

$$\nabla z_i = w_i^{\text{DM}} / (2(1 - p_i)) \times \frac{\partial L_{\text{CCE}}}{\partial z_i}.$$
$$w_i^{\text{DM}} = \exp(\beta p_i^{\lambda} (1 - p_i)) \Longrightarrow \psi_{\text{DM}} = \frac{1}{\lambda}$$
$$\lambda \ge 0 \Longrightarrow \psi_{\text{DM}} \in [0, 1).$$



Magnitude: Emphasis Density Function

• Emphasis density function:

$$w_{i}^{\text{DM}} = \exp(\beta p_{i}^{\lambda} (1 - p_{i})) \Longrightarrow \psi_{\text{DM}} = \frac{\lambda}{\lambda + 1}.$$

$$h(w_{i}^{\text{DM}}) = \frac{w_{i}^{\text{DM}}}{\int_{0}^{1} w_{i}^{\text{DM}} d_{p_{i}}} \Longrightarrow \int_{0}^{1} h(w_{i}^{\text{DM}}) d_{p_{i}} = 1.$$
(5)



Magnitude: Emphasis Density Function



Figure: An EDF is an example-level weighting function normalised by its integral over [0, 1].



Example weighting via EDFs Summary and definitions

Definition 1 (Emphasis Mode ψ). We define the emphasis mode to be p_i of examples whose weights are the largest, i.e., $\psi = \underset{p_i}{\operatorname{arg max}} w_i, \quad \psi \in [0, 1].$

For example, by 'emphasis mode is 0 in CCE' we mean those images with $p_i = 0$ own the highest weights.

Definition 2 (Emphasis Variance σ). $\sigma = E((w_i - E(w_i))^2)$, where $E(\cdot)$ denotes the expectation of a variable.





Figure: We observe noisy examples have much less p_i than clean ones, thus being more difficult examples.



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Core research questions [11]

- In Self LC, how much should we trust a learner to leverage its knowledge?
 - The trust score is fixed or updated stage-by-stage in prior work.
 - ProSelfLC modifies the target progressively, is end-to-end trainable, and requires negligible extra cost.
- 2 Should we penalise a low-entropy status or reward it?
 - OR methods penalise low entropy while LC rewards it.
 - ProSelfLC [11] redirects and promotes entropy minimisation.



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BEYOND SEMANTIC CLASS THE SIMILARITY STRUCTURE IN A LABEL DISTRIBUTION

A label distribution defines what to learn:

- Definition 1 (Semantic Class). Given a target label distribution q̃(x) ∈ ℝ^C, the semantic class is defined by arg max_i q̃(j|x), i.e., the class whose probability is the largest.
- Definition 2 (*Similarity Structure*). In CCE, LS and CP, a data point has an identical probability of belonging to other classes except for the semantic class. Instead, in LC, a target label distribution captures the probability difference of an example being predicted to every class. We define it to be the similarity structure of one example versus all training classes.



An overview of label (target) modification OR(LS and CP) + LC(Self LC and Non-self LC)



OR includes LS [8] and CP [6], which smoothes similarity structure:

- LS softens a target by adding a uniform label distribution.
- CP changes the probability 1 to a smaller value 1 ε in the one-hot target.
 The double-ended arrow means factual equivalence, because an output is definitely non-negative after a softmax layer.



An overview of label (target) modification OR(LS and CP) + LC(Self LC and Non-self LC)



- LC contains Self LC [5, 7, 9] and Non-self LC [4].
- The convex combination parameter ε defines how much a predicted label distribution is trusted.



Drawbacks of existing target modification Why Self LC to exploit a model's self knowledge?

- OR methods naively penalise confident outputs without leveraging easily accessible knowledge from other learners or itself.
- 2 Non-self LC relies on accurate auxiliary models.
- **3** Self LC:
 - It exploits its own knowledge;
 - It requires no extra learners;
 - However, how much should we trust a learner to leverage its knowledge?



Overview of existing variants of Self LC Without considering a model's knowledge grows as time goes

- 1 In bootstrapping, ϵ is fixed throughout the training process.
- 2 Joint Optimisation fully trusts a learner by setting $\epsilon = 1$, and uses stage-wise training to gradually train the model.
 - Stage-wise training requires a significant human intervention and is time-consuming in practice.
- **3** Requirements of improving Self LC
 - End-to-end trainable.
 - Negligible extra cost.
 - Modifies the target progressively and adaptively as training goes.



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To penalise or reward a low-entropy status?

- OR methods penalise low entropy ⇒ OR is against entropy minimisation principle.
- LC rewards a low-entropy status ⇒ LC defends entropy minimisation principle.
 - LC has the same principle as the widely used expectation-maximization (EM) algorithm.



Self Trust according to Training Time and Confidence

 ϵ indicates how much a predicted label distribution is trusted. For any x, we summarise the <code>loss and modified label</code>:

$$\begin{split} \mathcal{L}_{(\widetilde{\mathsf{q}}_{\text{ProSelfLC}}, \mathsf{p}; \, \epsilon_{\text{ProSelfLC}}) &= \mathrm{H}(\widetilde{\mathsf{q}}_{\text{ProSelfLC}}, \mathsf{p}) = \mathrm{E}_{\widetilde{\mathsf{q}}_{\text{ProSelfLC}}}(-\log \ \mathsf{p}), \\ \widetilde{\mathsf{q}}_{\text{ProSelfLC}} &= (1 - \epsilon_{\text{ProSelfLC}})\mathsf{q} + \epsilon_{\text{ProSelfLC}}\mathsf{p}, \\ \epsilon_{\text{ProSelfLC}} &= g(t) \times l(\mathsf{p}), \\ g(t) &= h(t/\Gamma - 0.5, B) \in (0, 1), \Rightarrow \text{Trusting learning time} \\ l(\mathsf{p}) &= 1 - \mathrm{H}(\mathsf{p})/\mathrm{H}(\mathsf{u}) \in (0, 1). \Rightarrow \text{Trusting sample confidence} \end{split}$$
(6)

t and Γ are the iteration (time) counter and the number of total iterations, respectively.

 $h(\cdot)$ is a logistic function where B controls its smoothness.



Training Dynamics On CIFAR-100 with asymmetric label noise r = 0.4.





Training Dynamics On CIFAR-100 with asymmetric label noise r = 0.4.





Training Dynamics On CIFAR-100 with asymmetric label noise r = 0.4.



(a) Entropy of clean subset.

(b) Entropy of noisy subset.

Figure: Should we penalise a low-entropy status or reward it?



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Summary

ProSelfLC:

- enhance the similarity structure information over training classes.
- correct the semantic classes of noisy label distributions.
- is the first method to trust self knowledge progressively and adaptively.
- 2 Our extensive experiments:
 - defend the entropy minimisation principle.

3 Code:

https://github.com/XinshaoAmosWang/ProSelfLC-CVPR2021



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Industrial research overview

- The focus is to solve real-world impactful applications. Publishing and sharing research is encouraged.
- To build AI toolboxes and a comprehensive AI pipeline to solve diverse applications by creating AI softwares and web applications, etc.



Source: https://dida.do/blog/data-centric-machine-learning



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Zenith AI research

model-centric AI + data-centric AI



AI System = Data + Model (Code)



Thanks for your attention. Questions and discussions are very welcome.

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